

## Original Research

# Comparison of Dynamic Parameters of Landing from Different Heights of Professional Elite Volleyball Players 

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#### Abstract

This study aims to compare the dynamic parameters of professional elite volleyball players when landing from different heights. 15 volleyball players selected based on availability participated in the study. The studied skill for different height was set to a percentage of the maximum jump elevation ( $100 \%-75 \%-50 \%$ ). A repeated measures ANOVA model was used to determine the measurements variance differences using SPSS software version 24 . The results showed that landing from higher height increased the angular velocity of the rotational axis of the foot while the peak of angular acceleration was lower at the highest elevation. The linear velocity peak also showed lower values at the highest elevation, while the linear acceleration increased with increasing landing elevation. Despite the insignificant effect of different height on the vertical ground reaction force (vGRF) factor, the peak of ankle joint torque in the anterior-posterior axis increased with increasing elevation. Similarly, the maximum ankle angle in the anterior-posterior axis was higher at high elevation than at low elevation. The results showed that volleyball players try to improve the absorption of energy by increasing the range of motion of the ankle joint in the anterior-posterior axis at high elevation.


Keywords: Landing Biomechanics, Kinetics, Kinematics, Ankle joint, Volleyball
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## INTRODUCTION

Volleyball is a non-collision sport, but performing repetitive high intensity movements has defined this sport as a sport with a relatively high prevalence of injury and more than $30 \%$ of musculoskeletal injuries [1]. Volleyball athletes need to move fast and score points with long jumps, precise dives, and sudden rerouting; for this reason, the possibility of lower limb injury is evident during displacements, jumps, and landings [2].
Landing following a jump can cause a force of impact 2 to 12 times the body's weight and is often a factor in lower limb injuries [3]. One-legged landing is a common occurrence in sports such as basketball, volleyball, football, and badminton [4]. In the jump-landing movement, the landing stage puts far more pressure on the body than the jumping stage [5]. Studies show that, on average, 60 repetitions of the jump-landing technique are performed per hour of volleyball, followed by a vertical ground reaction force (vGRF) equivalent to one to five times the bodyweight on the lower limb [6]. Since landing is one of the key basic skills in volleyball, examining kinetic factors to prevent injury and improve performance is of utmost importance.
Furthermore, examining the kinematic changes in the joint can be a good measure of the joint being in a highrisk position. On the other hand, related kinematic and kinetic parameters are affected by and related to each other. Therefore, the larger the kinematic changes of the joint, the greater the forces acting on it [7]. Ali et al., (2014) studied the kinematics and kinetics of one-legged landing from different heights and reported that the knee flexion angle in the sagittal plane, trunk flexion angle, and ground reaction force increase significantly with increasing landing elevation [8]. Basically, various aspects in the kinematic and kinetic evaluation of the ankle joint, especially in preventing injury and improving performance, have been considered by researchers, including stiffness [9], joint speed and angle [10], range of motion [11], acceleration [12], torque [12] and joint strength [13].
Kinematic and kinetic changes of jump and landing are affected by the intensity of the jump [14,15]. Volleyball players have to have different jump intensity depending on their playing position changes. Thus, players must adjust their jump intensity according to the team strategy to receive the ball on the net, spike, or block. Therefore, jump elevation is one of the essential and influential factors in the biomechanical analysis of landing. However, up until now, the dynamic changes of jumping at different heights have not been sufficiently examined.
$52 \%$ of volleyball players experience one or more injuries during a season [16]. Due to this high prevalence rate, it is important to investigate the risk factors for injury since most of these injuries occur when landing from different heights post jump. It is also necessary to fully understand the dynamic mechanisms of landing when jumping from a different height to improve performance. Therefore, the present study aimed to compare the dynamic parameters of professional elite volleyball players when landing from different heights.

## MATERIAL AND METHODS

Subjects of the present study were 15 healthy male volleyball players with a mean age of $18.23 \pm 2.3$ years, a height of $183 \pm 6.3$, a weight of $64.72 \pm 14.12 \mathrm{~kg}$, and 3 to 5 years of experience in national competitions, selectively chosen based on availability. After a complete explanation of the research objectives and the method of implementation, the players' consent to participate in this research was obtained. This research has an ethics code number IR.SSRC.REC.1399.141. A force plate (Kistler, 1000 HZ ) was used to record kinetic information. This device was installed in the middle of the 20 -meter runway, invisible to the participants. Four cameras (japan, JVC, 200 Hz ) were parachuted around the force screen for 3D evaluation. Passive markers ( 10 mm , made in Germany) were used to form the body system. Anatomical markers to determine the kinematic model of the ankle joint included 10 inactive markers with dimensions of 22 mm made in Germany. They were attached to the landmark of the first metatarsal, the fifth metatarsal, second toe, heel, medial and lateral malleolus, medial and lateral epicondyle, and the three-point cluster. After static imaging, the first metatarsal markers, fifth metatarsal markers, heel, and three-point cluster remained as tracking markers on the subject's body. Prior to the start of the running test, the reference coordinates were imaged by all cameras using a labelled cube with the force plate placed in the center of the reference coordinates. The video camera was then synchronized with the force screen. The beginning and end of the
movement were determined using a force plate by applying a force of 5 N [17]. To use the camera data recorded, the raw data was filtered through MATLAB software, version 2013, using Butterworth secondorder zero-lag low-pass method at a cut-off frequency of 45 . Cut-off frequency was determined using the residual analysis technique for kinematic and kinetic data. Subjects first performed individual warm-ups, including jogging at an optional speed and landing from a 30 cm box. The maximum jump of the subjects was measured using the Sargent jump test. Then, 50, 75, and 100 percent of the maximum jumps of each subject were calculated. Accordingly, the box elevation was determined for each subject in three landings. Then, after the rest interval, the landing motion test was performed. The elevation of the box was determined according to the percentages obtained from each Sargent test (the box was made with iron bars in such a way that it can be adjusted in elevation) (Figure 1 and 2), then each participant jumped 3 times from each elevation in 3-minute intervals between individual jumps so that after landing, the subject's foot was on the force plate. Using the Cardan-Euler angles system, the angles of the limbs in each of the three-dimensional planes were calculated. Peak moment variables, ground reaction force peak, ankle peak force, linear velocity peak, linear acceleration peak, angular velocity peak, angular acceleration peak, equilibrium time, and peak range of motion of the ankle joint were calculated and used for statistical measures. All steps of statistical analysis were performed using SPSS software version 24. Shapiro-wilk test was used to assess the normality of data distribution. Similarly, repeated measures analysis of variance was used to determine the differences between the measurements, and the Bonferroni post hoc test was used to determine the differences within the group. All stages of statistical tests were evaluated and performed at the significance level of $\mathrm{P} \leq 0.05$.


Figure 1. Static state in 50, 75, $100 \%$ height


Figure 2. Landing from 50, 75, $100 \%$ height

## RESULTS

The results of statistical analysis showed that the peak torque of the ankle in the sagittal $(\mathrm{P}=0.005)$ and horizontal $(\mathrm{P}=0.003)$ plates in landing from three different heights are significantly different (Table 1$)$. Similarly, maximum ankle angle in sagittal plates ( $\mathrm{P}=0.017$ ) and minimum ( $\mathrm{P}=0.044$ ), peak angular velocity of ankle in frontal plates ( $\mathrm{P}=0.000$ ), linear ankle velocity in sagittal plates $(\mathrm{P}=0.000)$ and horizontal ( $\mathrm{P}=0.025$ ), The linear velocity peak of the foot in the sagittal ( $\mathrm{P}=0.039$ ), frontal $(\mathrm{P}=0.000)$ and horizontal $(\mathrm{P}=0.029)$ planes in landing from three different height are significantly different (Table 2). Finally, the linear acceleration peak of the ankle in the horizontal plates $(P=0.003)$, the linear acceleration peak of the foot in the sagittal plates $(\mathrm{P}=0.008)$, the frontal $(\mathrm{P}=0.003)$ and horizontal $(\mathrm{P}=$ 0.018 ), the linear peak acceleration of the shank (crus) in the horizontal plates ( $\mathrm{P}=0.033$ ), peak angular acceleration of ankle in sagittal plates $(P=0.004)$, peak angular acceleration of foot in sagittal plates $(P=$ 0.015 ), frontal ( $\mathrm{P}=0.003$ ) and peak angular acceleration of shank in sagittal plates $(\mathrm{P}==0.016$ ) was significantly different between three landings from different height (Table 3). Due to the large volume of
statistical data, kinematic and kinetic parameters that did not show significant differences due to landing from different heights were not reported.

Table (1). Mean, standard deviation, parameters related to lower limb joint torque at landing from three different heights

| Variable | Maximum <br> Elevation \% | Standard mean and variance | Intragroup pvalue | Effect Size (eta ${ }^{2}$ ) | Bonferoni test p-value |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Peak ankle torque Saggital (Nm/BW) | 50 | 0.36 (0.3) | * 0.005 | 0.32 | 50-75 | +0.022 |
|  | 75 | 0.89 (0.63) |  |  | 75-100 | +1.00 |
|  | 100 | 0.85 (0.47) |  |  | 50-100 | +0.011 |
| Peak ankle torque Horizontal ( $\mathrm{Nm} / \mathrm{BW}$ ) | 50 | 0.08 (0.07) | * 0.003 | 0.38 | 50-75 | +0.017 |
|  | 75 | 0.2 (0.12) |  |  | 75-100 | +0.021 |
|  | 100 | 0.1 (0.01) |  |  | 50-100 | 0.827 |

* $\mathrm{P} \leq 0 / 05$

Table (2). Mean and Standard deviation of parameters related to angular displacement, linear and angular velocity of lower limbs in landing from three different heights

| Variable | Maximum <br> Elevation \% | Standard mean and variance | Intragroup pvalue | Effect Size (eta ${ }^{2}$ ) | Bonferoni test pvalue |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Maximum ankle angle -Sagittal (dgr) | 50 | 24.46 (6.63) | * 0.017 | 0.2 | 50-75 | 0.499 |
|  | 75 | 24.56 (4.69) |  |  | 75-100 | 0.443 |
|  | 100 | 26.92 (4.6) |  |  | 50-100 | *0.015 |
| Minimum ankle angle- Sagittal (dgr) | 50 | -14.91 (0.08) | * 0.044 | 0.25 | 50-75 | 0.243 |
|  | 75 | -22.30 (0.17) |  |  | 75-100 | 1.00 |
|  | 100 | -23.83 (0.9) |  |  | 50-100 | 0.087 |
| Peak angular velocity of the foot- Frontal ( $\mathrm{rad} / \mathrm{s}$ ) | 50 | 0.03 (0.15) | * 0.00 | 0.43 | 50-75 | *0.004 |
|  | 75 | 0.08 (0.12) |  |  | 75-100 | 1.00 |
|  | 100 | 0.08 (0.24) |  |  | 50-100 | *0.005 |
| Peak linear velocity of the ankle- Saggital ( $\mathrm{m} / \mathrm{s}$ ) | 50 | 0.02 (0.01) | * 0.00 | 0.14 | 50-75 | *0.046 |
|  | 75 | 0.04 (0.01) |  |  | 75-100 | *0.002 |
|  | 100 | 0.01 (0.007) |  |  | 50-100 | 0.138 |
| Peak linear velocity of the ankleHorizontal (m/s) | 50 | 0.037 (0.02) | * 0.025 | 0.34 | 50-75 | *0.044 |
|  | 75 | 0.023 (0.008) |  |  | 75-100 | 0.906 |
|  | 100 | 0.027 (0.014) |  |  | 50-100 | 0.33 |
| Peak linear velocity of the foot - Sagittal ( $\mathrm{m} / \mathrm{s}$ ) | 50 | 0.02 (0.018) | * 0.039 | 0.24 | 50-75 | 0.402 |
|  | 75 | 0.01 (0.008) |  |  | 75-100 | 0.284 |
|  | 100 | 0.008 (0.002) |  |  | 50-100 | 0.055 |
| Peak linear velocity of the foot- Frontal ( $\mathrm{m} / \mathrm{s}$ ) | 50 | 0.182 (0.11) | * 0.00 | 0.44 | 50-75 | 0.317 |
|  | 75 | 0.11 (0.08) |  |  | 75-100 | 0.011 |
|  | 100 | 0.034 (0.01) |  |  | 50-100 | *0.001 |


| Peak linear <br> velocity of the <br> foot- Horizontal <br> $(\mathrm{m} / \mathrm{s})$ | 75 | $0.032(0.02)$ |  |  | $50-75$ | $* 0.042$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: |
|  | 100 | $0.051(0.02)$ |  | 0.0029 | 0.22 | $75-100$ | 00.946

* $\mathrm{P} \leq 0 / 05$

Table (3). Mean and standard deviation of parameters related to linear and angular acceleration of the lower limbs in landing from three different heights

| Variable | Maximum <br> Elevation \% | Standard mean and variance | Intragroup pvalue | Effect Size (eta ${ }^{2}$ ) | Bonferoni test pvalue |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Peak linear acceleration of the ankleHorizontal ( $\mathbf{m} / \mathbf{s}^{\mathbf{2}}$ ) | 50 | 0.031 (0.2) | * 0.003 | 0.34 | 50-75 | 0.151 |
|  | 75 | 0.64 (0.5) |  |  | 75-100 | * 0.011 |
|  | 100 | 0.2 (0.08) |  |  | 50-100 | 0.141 |
| Peak linear acceleration of the footSagittal ( $\mathrm{m} / \mathrm{s}^{2}$ ) | 50 | 0.14 (0.08) | * 0.008 | 0.29 | 50-75 | 0.071 |
|  | 75 | 0.26 (0.17) |  |  | 75-100 | 0.061 |
|  | 100 | 0.14 (0.9) |  |  | 50-100 | 1.00 |
| Peak linear acceleration of the foot- Frontal $\left(\mathrm{m} / \mathrm{s}^{2}\right)$ | 50 | 0.12 (0.101) | * 0.003 | 0.34 | 50-75 | *0.017 |
|  | 75 | 0.34 (0.21) |  |  | 75-100 | 1.00 |
|  | 100 | 0.32 (0.18) |  |  | 50-100 | *0.013 |
| Peak linear acceleration of the footHorizontal ( $\mathrm{m} / \mathrm{s}^{2}$ ) | 50 | 0.97 (0.51) | * 0.018 | 0.25 | 50-75 | *0.038 |
|  | 75 | 1.46 (1.24) |  |  | 75-100 | 0.367 |
|  | 100 | 1.43 (0.99) |  |  | 50-100 | 0.419 |
| Peak linear acceleration of the shank (crus)- <br> Horizontal $\left(\mathrm{m} / \mathrm{s}^{2}\right)$ | 50 | 0.94 (0.35) | * 0.033 | 0.21 | 50-75 | *0.039 |
|  | 75 | 1.75 (1.08) |  |  | 75-100 | 1.00 |
|  | 100 | 1.53 (1.14) |  |  | 50-100 | 0.29 |
| Peak angular acceleration of the ankleSagittal ( $\mathrm{rad} / \mathrm{s}^{2}$ ) | 50 | 4.46 (3.54) | * 0.004 | 0.39 | 50-75 | 0.186 |
|  | 75 | 8.52 (6.71) |  |  | 75-100 | *0.003 |
|  | 100 | 1.69 (1.1) |  |  | 50-100 | *0.045 |
| Peak angular acceleration of the footSagittal ( $\mathrm{rad} / \mathrm{s}^{2}$ ) | 50 | 3.61 (2.48) | * 0.015 | 0.31 | 50-75 | 0.539 |
|  | 75 | 5.59 (4.57) |  |  | 75-100 | 0.01 |
|  | 100 | 1.63 (0.81) |  |  | 50-100 | *0.039 |
| Peak angular acceleration of the foot- Frontal $\left(\mathrm{rad} / \mathrm{s}^{2}\right)$ | 50 | 1.53 (0.87) | * 0.003 | 0.34 | 50-75 | *0.042 |
|  | 75 | 3.57 (2.1) |  |  | 75-100 | 0.45 |
|  | 100 | 1.52 (0.87) |  |  | 50-100 | 1.00 |
| Peak angular acceleration of the shank | 50 | 2.24 (0.35) | * 0.016 | 0.28 | 50-75 | 0.055 |
|  | 75 | 4.32 (3.11) |  |  | 75-100 | 0.92 |


| (crus)- Sagittal <br> $\left(\mathrm{rad} / \mathrm{s}^{2}\right)$ | 100 | $2.69(1.95)$ |  | $50-100$ | 1.00 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |

* $\mathrm{P} \leq 0 / 05$


## Discussion

This study aimed to compare the performance of professional elite volleyball players when landing from different heights using modern kinetic and kinematic methods. The results showed that the height of landing elevation affects the kinematics of the ankle joint and the limbs of the foot and shank in three axes of motion. As the elevation increases, the linear velocity of the ankle joint and foot in the anterior-posterior axis decreases to the maximum extent. Most linear velocity changes occur in the anterior-posterior axis, while linear acceleration changes occur with increasing elevation in all three axes of motion. These results clearly show that the trend of changes in the linear peak velocity and linear acceleration in the ankle joint and foot limb when landing from different heights is not the same.

Research has shown that one of the most important forces on the body when landing is the vertical force of the ground reaction, which is mentioned as an indicator of the risk of injury to the joints of the ankle, knee, thigh and spine [18]. The factors that affect the magnitude of vertical ground reaction force (vGRF) include velocity, landing elevation, shoe type, body weight, position and landing surface, and landing strategy. Increasing the elevation increases the reaction force of the ground and increases the load on the joints [19, 20]. The results showed that the higher the ground reaction force, the higher the torque in the knee joint and the ankle joint; therefore, the amount of damage to these two joints may increase with increasing reaction forces. There is a relationship between the maximum torque of the knee joint and the ankle joint with the maximum ground reaction force. Increased torque increases joint damage. As the ground reaction force increases, the amount of joint torque and, consequently, the amount of load (ROL) on the knee joint and the ankle joint increases. It is likely that as the amount of load applied to the joint increases, the amount of damage to the joint increases as well [21]. In the results of the present study, with increasing landing elevation, the peak torque of the ankle joint increases, which is consistent with the results of De wit et al. (1995), Chappell et al. (2002), and Fattahi et al. (2017).

According to research, with increasing elevation, the reaction force of the ground at the moment of contact also increases; as a result, with increasing landing elevation, the maximum angle of flexion of the knee was observed [22].The relationship between landing elevation and ground reaction force, knee flexion angle, angular velocity, and joint strength during bipedal landing was evaluated. The results showed a direct relationship between ground reaction force and knee flexion intensity with increasing elevation, meaning that increasing the landing elevation increases the ground reaction force and the knee flexion angle [23].The present study was performed by landing on one foot and on the ankle joint. As a result, it is inconsistent with the research of Ali et al. (2014) and Yeow et al. (2009) but is consistent in increasing the joint angle and increasing the angular velocity.

Based on the relationship between work and energy, a decrease in angular velocity can reflect a decrease in energy absorption $[24,25]$. When the body is being worked, changes in the angular component of the body's kinetic energy occur as an unbalanced torque in a range of motion. On landing, the angular velocity of the joints is also reduced to zero. A peak above angular velocity reflects more angular kinetic energy of rotating objects. More negative work must be done in the form of torque applied in the opposite direction of rotation to reduce the angular kinetic energy to zero. The source of torque to reduce the angular velocity in the ankle is the extraversion activity in the posterior muscles of the ankle. Therefore, there may be a hypothesis that more extrinsic activity of the dorsiflexor muscles is required to reduce the angular velocity
of the ankle joint when descending from a higher altitude compared to descending from a lower altitude [26]. A study of kinematics and the kinetics of the ankle joint during landing was conducted to compare the superior foot with the non-superior foot. Subjects performed landing movements from three different heights $(0.32 \mathrm{~m}, 0.52 \mathrm{~m}$, and 0.72 m$)$. This study measured ground reaction force, and ankle joint kinematics, in both Legs. The results showed that the maximum angular velocities of dorsiflexion and abduction are significantly higher in the superior ankle [27]. The findings reported in the present study are consistent with results reported by Niu et al (2011) regarding the increase in angular velocity for landings on the superior foot.

Changes in limb speed and acceleration during landing are significant and can be considered as a cause of injury; for example, anterior cruciate ligament injury is very common in unbalanced landing patterns [28]. As the height increases, the maximum amount of changes in the linear velocity of the ankle joint and limb in the anterior-posterior axis decreases. The results showed that the linear velocity in different axes of motion could vary depending on the landing elevation. The peak of linear velocity in the ankle joint in the rotational axis was achieved at a lower height, while it was achieved at $75 \%$ elevation in the anteriorposterior axis. Increasing the landing speed due to high elevation does not necessarily lead to damage if proper landing techniques are used. An increase in changes in vertical velocity is associated with an increase in the vertical ground reaction force [29]. In the present study, the peak of linear velocity was reduced at high elevation. Thus it is inconsistent with the research of Dai et al (2019).
The results showed that for volleyball players, landing from a higher height increases the angular velocity of the foot limb in the rotational axis, increases the peak torque of the ankle joint in the anterior-posterior axis, increases the ankle angle in the anterior-posterior axis, and also increases the peak of linear acceleration. While the peak of angular acceleration and the peak of linear velocity at the highest elevation showed lower values. Therefore, coaches and athletes can use training methods to strengthen the selected ankle muscles by considering the optimal implementation of landing strategies with an injury prevention approach.

## CONCLUSION

The results showed that volleyball players try to improve the absorption of energy by increasing the range of motion of the ankle joint in the anterior-posterior axis at high elevation.

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## مقايسه پارامترهاى ديناميكى فرود از ار تفاع هاى مختلف واليباليست هاى نخبه حرفه اى

$$
\begin{aligned}
& \text { ا- گروه بيومكانيك ورزشى، واحد تهر ان مركزى، دانشگاه آزاد اسلامى، تهران، ايران }
\end{aligned}
$$

چكيده
هدف از انجام پ夫وهش حاضر مقايسه عملكرد واليباليست هاى نخبه حرفه ای هنگام فرود از ارتفاع هاى مختلف با استفاده از روش




 كه فرود از ارتفاعهاى بالاتر در واليباليستها سبب افز افزايش سرعت زاويها زاويهاى در بالاترين ارتفاع كمتر بود. همينطور اوج سرعت خطى نيز در در بالاترين ارتفاع ارتاع مقادير كمترى را نشان داد داد در حاليكه شتاب


 ارتفاع بالا سعى در جذب انرزى بهتر دارند. هم چنين، تغييرات بيشتر در متغيرهاى سرعت و شتاب زاويهاى دار در ارتفاع پايينتر نشان از انتقال انرثى به اندامهاى بالاتر دارد.

وازگان كليدى: بيومكانيك فرود ، كينتيك و كينماتيك مفصل مجّ پا ، واليبال

